

贵州大学 计算机科学与技术学院 实验报告

院(系)名称	示范性软件学院	班级	软工 206	课程名称	Linux 系统
实验名称	实验五	日期	11 月 18 日	指导教师	王老师
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1. 实验名称
进程通信

2. 实验目的
熟悉 Linux 进程之间信号、管道、消息队列（信号量、共享内存）等通信的实现方法。

2. 内容（原理、方法）
分别使用信号、管道和消息队列实现进程之间的通信。

3. 结果、分析与建议
- 基于信号的进程通信

```
#include<stdio.h>
#include<signal.h>
#include<unistd.h>
#include<stdlib.h>
#include<sys/wait.h>
int wait_mark;
void waiting(),stop();
void main()
{
    int p1, p2;
    signal(SIGINT,stop);
    while((p1=fork())!=-1);
    if(p1>0) /*在父进程中*/
    { /* (1) */
        while((p2=fork())!=-1);
        if(p2>0) /*在父进程中*/
        { /*(2) */
            wait_mark=1;
            waiting(0);
            kill(p1,10);
            kill(p2,12);
            wait(NULL );
            wait(NULL );
            printf("parent process is killed!\n");
            exit(0);
        }
    }
}
```

```

        exit(0);
    } else /*在子进程2中*/
    {
        wait_mark=1;
        signal(12, stop);
        waiting();
        lockf(1, 1, 0);
        printf("child process 2 is killed by parent!\n");
        lockf(1, 0, 0);
        exit(0);
    }
} else /*在子进程1中*/
{
    wait_mark=1;
    signal(10, stop);
    waiting();
    lockf(1, 1, 0);
    printf("child process 1 is killed by parent!\n");
    lockf(1, 0, 0);
    exit(0);
}
}

void waiting()
{
    while(wait_mark!=0);
}
void stop()
{
    wait_mark=0;
}

```

```

[root@hadoop100 experiment_005]# gcc signal.c -o signal
[root@hadoop100 experiment_005]# ./signal
^Cchild process 2 is killed by parent!
child process 1 is killed by parent!
parent process is killed!
[root@hadoop100 experiment_005]# █

```

- 把参考程序 signal(SIGINT, stop) 放在 /*(1) */ 和 /*(2) */ 位置

```

#include<stdio.h>
#include<signal.h>
#include<unistd.h>
#include<stdlib.h>
#include<sys/wait.h>
int wait_mark;
void waiting(),stop();
void main()
{
    int p1, p2;
    signal(SIGINT,stop);
    while((p1=fork())!=-1);
    if(p1>0) /*在父进程中*/
    {
        signal(SIGINT,stop);
        while((p2=fork())!=-1);
        if(p2>0) /*在父进程中*/
        {
            signal(SIGINT,stop);
            wait_mark=1;
            waiting(0);
            kill(p1,10);
            kill(p2,12);
            wait(NULL );
            wait(NULL );
            printf("parent process is killed!\n");
            exit(0);
        } else /*在子进程2中*/

```

```

        exit(0);
    } else /*在子进程2中*/
    {
        wait_mark=1;
        signal(12,stop);
        waiting();
        lockf(1,1,0);
        printf("child process 2 is killed by parent!\n");
        lockf(1,0,0);
        exit(0);
    }
} else /*在子进程1中*/
{
    wait_mark=1;
    signal(10,stop);
    waiting();
    lockf(1,1,0);
    printf("child process 1 is killed by parent!\n");
    lockf(1,0,0);
    exit(0);
}
}

```

```
void waiting()
{
    while(wait_mark!=0);
}
void stop()
{
    wait_mark=0;
}
```

```
[root@hadoop100 experiment_005]# vim signal2.c
[root@hadoop100 experiment_005]# gcc signal2.c -o signal2
[root@hadoop100 experiment_005]# ./signal2
^Cchild process 2 is killed by parent!
child process 1 is killed by parent!
parent process is killed!
[root@hadoop100 experiment_005]#
```

该程序段前面部分用了两个 `wait(0)`,为什么?

`wait(0)` 暂时停止目前进程的执行,直到信号来到或子进程结束,如果在调用 `wait(0)` 时子进程已经结束,则 `wait(0)` 会立即返回子进程结束状态值。

该程序段中每个进程退出时都用了语句 `exit(0)`,为什么?

为了进程的正常终止,在正常终止时, `exit()` 函数返回进程结束状态。

- 基于管道的进程通信
 - o 读管道程序

```

#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>
#include <sys/stat.h>
#include <fcntl.h>
#include <string.h>
#include <errno.h>

#define BUFFER_SIZE 1024

int main(int argc, char **argv)
{
    int fd;

    if (argc < 2)
    {
        fprintf(stdout, "Usage: %s <filename>\n", argv[0]);
        exit(1);
    }

    if ((fd = open(argv[1], O_RDONLY)) < 0)
    {
        fprintf(stderr, "open fifo %s for reading failed: %s\n", argv[1], strerror(errno));
        exit(1);
    }

    fprintf(stdout, "open fifo %s for reading succeeded.\n", argv[0]);
    char buffer[BUFFER_SIZE];
    ssize_t n;

```

```

while (1)
{
    again:
    if ((n = read(fd, buffer, BUFFER_SIZE)) < 0)
    {
        if (errno == EINTR)
        {
            goto again;
        }
        else
        {
            fprintf(stderr, "read failed on %s: %s\n", argv[1], strerror(errno));
            exit(1);
        }
    }
    else if (n == 0)
    {
        fprintf(stderr, "peer closed fifo.\n");
        break;
    }
    else
    {
        buffer[n] = '\0';
        fprintf(stdout, "read %d bytes from fifo: %s\n", n, buffer);
    }
}
return 0;

```

○ 写管道程序

```
#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>
#include <sys/stat.h>
#include <fcntl.h>
#include <signal.h>
#include <string.h>
#include <errno.h>

#define BUFFER_SIZE 1024

void signal_handler(int s);

int main(int argc, char **argv)
{
    int fd;

    if (argc < 2)
    {
        fprintf(stdout, "Usage: %s <filename>\n", argv[0]);
        exit(1);
    }

    signal(SIGPIPE, signal_handler);

    if ((fd = open(argv[1], O_WRONLY)) < 0)
    {
        fprintf(stderr, "open fifo %s for writting failed: %s\n", argv[1], strerror(errno));
        exit(1);
    }
}
```

```

fprintf(stdout, "open fifo %s for writing succeeded.\n", argv[0]);

char buffer[BUFFER_SIZE];
ssize_t n;

while (fgets(buffer, BUFFER_SIZE, stdin))
{
again:
    if ((n = write(fd, buffer, strlen(buffer))) < 0)
    {
        if (errno == EINTR)
        {
            goto again;
        }
        else
        {
            fprintf(stderr, "write() failed on fifo: %s\n", strerror(errno));
            break;
        }
    }
}

return 0;
}

void signal_handler(int s)
{
    fprintf(stdout, "Caught signal %d\n", s);
}

```

○ 创建管道程序

```

#include <stdio.h>
#include <stdlib.h>
#include <sys/stat.h>
#include <string.h>
#include <errno.h>

int main(int argc, char **argv)
{
    if (argc < 2)
    {
        fprintf(stdout, "Usage: %s <filename>\n", argv[0]);
        exit(1);
    }

    if (mkfifo(argv[1], 0644) < 0)
    {
        fprintf(stderr, "mkfifo() failed: %s\n", strerror(errno));
        exit(1);
    }

    return 0;
}

```

○ 编译运行

```

[root@hadoop100 experiment_005]# gcc read_fifo.c -o read_fifo
[root@hadoop100 experiment_005]# gcc write_fifo.c -o write_fifo
[root@hadoop100 experiment_005]# gcc create_fifo.c -o create_fifo
[root@hadoop100 experiment_005]# ./create_fifo /tmp/f1

```

```

[root@hadoop100 experiment_005]# ll /tmp
总用量 588
prw-r--r--. 1 root root    0 11月 20 11:45 f1
drwx-----. 2 root root   24 11月 12 19:57 ssh-GpVEgnbbHFht
drwx-----. 2 root root   24 11月 18 20:16 ssh-Jzzvc79l1VFfa
drwx-----. 2 root root   24 11月 20 11:16 ssh-KVtD791sJ4aZ

```

```

[root@hadoop100 experiment_005]# ./write_fifo /tmp/f1
open fifo ./write_fifo for writing succeeded.
how^H^H^H^H^H
hello, god !

```

另一终端

```
[root@hadoop100 experiment_005]# ./read_fifo /tmp/f1
open fifo ./read_fifo for reading succeeded.
read 9 bytes from fifo: how

read 13 bytes from fifo: hello, god !
```

断开写进程

```
^C
[root@hadoop100 experiment_005]#
```

读进程也自动断开

```
[root@hadoop100 experiment_005]# ./write_fifo /tmp/f1
open fifo ./write_fifo for writting succeeded.
how^H^H^H^H^H
hello, god !
nice
Caught signal 13
write() failed on fifo: Broken pipe
[root@hadoop100 experiment_005]#
```

- 基于共享内存的进程通信
 - o 共享内存读

```
#include <stdio.h>
#include <stdlib.h>
#include <sys/types.h>
#include <sys/shm.h>
#include <sys/ipc.h>
#include <unistd.h>
#include <signal.h>
#include <errno.h>

#define N 1024

typedef struct
{
    int pid;
    char buf[N];
} shmbuf;

void handler(int signo)
{
    return;
}

int main(int argc, char *argv[])
{
    int shmid;
    key_t key;
```

```

pid_t pid;
shmbuf *shmaddr;

signal(SIGUSR1, handler);
if ((key = ftok(".", 'a')) < 0)
{
    perror("fail to ftok");
    exit(-1);
}
if((shmid = shmget(key, sizeof(shmbuf), IPC_CREAT|IPC_EXCL|0666)) < 0)
{
    if (errno == EEXIST)
    {
        shmid = shmget(key, sizeof(shmbuf), 0666);
        shmaddr = (shmbuf *)shmat(shmid, NULL, 0);
        pid = shmaddr->pid;
        shmaddr->pid = getpid();
        kill(pid, SIGUSR1);
    }
    else
    {
        perror("fail to shmget");
        exit(-1);
    }
}

```

```

}
}
else
{
    shmaddr = (shmbuf *)shmat(shmid, NULL, 0);
    shmaddr->pid = getpid();
    pause();
    pid = shmaddr->pid;
}

while ( 1 )
{
    pause();
    if ( strncmp(shmaddr->buf, "quit", 4) == 0)
    {
        break;
    };
    printf("message from shm : %s", shmaddr->buf);
    usleep(100000);
    kill(pid, SIGUSR1);
}
shmdt(shmaddr);

return 0;

```

○ 共享内存写

```
#include <stdio.h>
#include <stdlib.h>
#include <sys/types.h>
#include <sys/shm.h>
#include <sys/ipc.h>
#include <unistd.h>
#include <signal.h>
#include <errno.h>
#include <string.h>

#define N 1024

typedef struct
{
    int pid;
    char buf[N];
} shmbuf;

void handler(int signo)
{
    return;
}

int main(int argc, char *argv[])
{
    int shmid;
```

```
key_t key;
pid_t pid;
shmbuf *shmaddr;

signal(SIGUSR1, handler);
if ((key = ftok(".", 'a')) < 0)
{
    perror("fail to ftok");
    exit(-1);
}
if((shmmid = shmget(key, sizeof(shmbuf), IPC_CREAT|IPC_EXCL|0666)) < 0)
{
    if (errno == EEXIST)
    {
        shmmid = shmget(key, sizeof(shmbuf), 0666);
        shmaddr = (shmbuf *)shmat(shmmid, NULL, 0);
        pid = shmaddr->pid;
        shmaddr->pid = getpid();
        kill(pid, SIGUSR1);
    }
    else
    {
        perror("fail to shmget");
        exit(-1);
    }
}
```

```

    }
    exit(-1);
}
else
{
    shmaddr = (shmbuf *)shmat(shmid, NULL, 0);
    shmaddr->pid = getpid();
    pause();
    pid = shmaddr->pid;
}

while ( 1 )
{
    printf("please input : ");
    fgets(shmaddr->buf, N, stdin);
    kill(pid, SIGUSR1);
    if (strncmp(shmaddr->buf, "quit", 4) == 0)
    {
        break;
    }
    pause();
}
sleep(1);
shmdt(shmaddr);
shmctl(shmid, IPC_RMID, NULL);
return 0;
}

```

○ 运行代码

```

[root@hadoop100 experiment_005]# gcc shm_read.c -o shm_read
[root@hadoop100 experiment_005]# gcc shm_write.c -o shm_write

```

```

[root@hadoop100 experiment_005]# ./shm_write
please input : how dare you

```

```

[root@hadoop100 experiment_005]# ./shm_read
message from shm : how are
message from shm : how dare you

```

```
[root@hadoop100 experiment_005]# ipcs -m
----- 共享内存段 -----
键          shmid      拥有者  权限    字节      nattch  状态      目标
0x00000000  9           root    777     16384     1       目标
0x00000000  10          root    777     2129920  2       目标
0x00000000  18          root    600     524288   2       目标
0x00000000  19          root    600     524288   2       目标
0x00000000  20          root    777     2129920  2       目标
0x00000000  21          root    600     524288   2       目标
0x61034262  22          root    666     1028     1
```

4. 附录(如源程序)
代码见上方截图